

Discrete Mathematics and Algebra

Linear Algebra - Example Population

Arno Kimeswenger

Institute for Mathematics and Statistics
University of Applied Sciences Wiener Neustadt

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Mathematical Model of Population Growth

- Three different species: plants x_t , rabbits y_t and foxes z_t

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- We discuss discrete model for time steps $0, 1, 2, \dots$, e.g.
 - $x_2 = 105$ means in year 2 there is about 105 tonnes plant biomass
 - $y_3 = 58$ means in year 3 there are 58 individuals in rabbit population,
 - $z_7 = 29$ means in year 7 there are 29 individuals in fox population

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 - $y_3 = 58$ means in year 3 there are 58 individuals in rabbit population,
 - $z_7 = 29$ means in year 7 there are 29 individuals in fox population
- **Plant population** $x_0 = 100$ and $x_{t+1} = 1.7x_t - 0.006x_t^2 - 0.001x_t y_t$
 - **Initial condition** $x_0 = 100$ tonnes
 - **Is increasing due to reproduction** $\Rightarrow +1.7x_t$
 - **Plants fight for space therefore reduction** $\Rightarrow -0.006x_t^2$
Square makes sense: x_t is small \Rightarrow no real fight but x_t large \Rightarrow fight for space
 - **Plants are food for rabbits therefore reduction** $\Rightarrow -0.001x_t y_t$
Product makes sense: lots of food x_t and many eaters y_t both amplify reduction

Mathematical Model of Population Growth

- **Rabbit population** $y_0 = 70$ and $y_{t+1} = 0.99y_t + 0.003x_t y_t - 0.012y_t z_t$
 - Initial condition $y_0 = 70$ rabbits
 - Reduction due to natural death $+0.99y_t$ (minus 1%)
 - Lots of food (plants, x_t) increase population $+0.003x_t y_t$
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- **Fox population** $z_0 = 30$ and $z_{t+1} = 0.975z_t + 0.0003y_t z_t$
 - Initial condition $z_0 = 30$ foxes
 - Reduction due to natural death $+0.975z_t$ (minus 2.5%)
 - Lots of food (rabbits y_t) increase population $+0.0003y_t z_t$

Mathematical Model of Population Growth

- **Final non-linear model**

$$x_{t+1} = 1.7x_t - 0.006x_t^2 - 0.001x_t y_t$$

$$y_{t+1} = 0.99y_t + 0.003x_t y_t - 0.012y_t z_t$$

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- **Initial conditions $x_0 = 100$, $y_0 = 70$ and $z_0 = 30$**

Mathematical Model of Population Growth

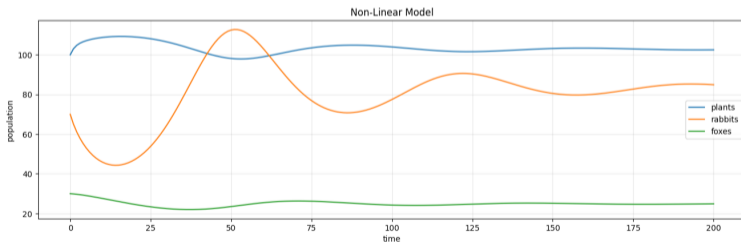
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Mathematical Model of Population Growth

- **Fixed point/equilibrium:** no change i.e. find x_t, y_t and z_t such that

$$x_t = 1.7x_t - 0.006x_t^2 - 0.001x_t y_t \quad \text{I}$$

$$y_t = 0.99y_t + 0.003x_t y_t - 0.012y_t z_t \quad \text{II}$$

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- **More interesting: III: $y_t \approx 83.33 \Rightarrow$ I: $x_t \approx 102.78 \Rightarrow$ II: $z_t = 24.86$**

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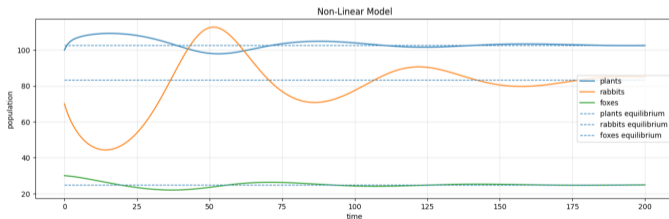
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Linear Mathematical Model of Population Growth

- Non-linear problems are complicated therefore find good linear approximation
- Using some techniques (2nd semester, Taylor series) we get approximation

$$\begin{pmatrix} x_{t+1} \\ y_{t+1} \\ z_{t+1} \end{pmatrix} = \begin{pmatrix} 102.78 \\ 83.33 \\ 24.86 \end{pmatrix} + \begin{pmatrix} 0.38 & -0.10 & 0.00 \\ 0.25 & 1.00 & -1.00 \\ 0.00 & 0.01 & 1.00 \end{pmatrix} \cdot \begin{pmatrix} x_t - 102.78 \\ y_t - 83.33 \\ z_t - 24.86 \end{pmatrix}$$

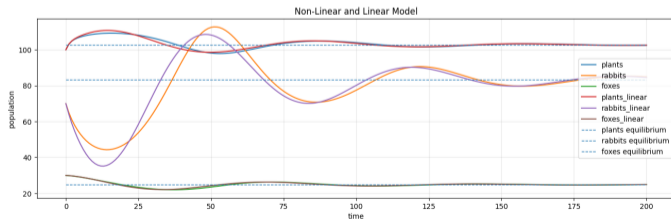
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- Initial conditions $x_0 = 100$, $y_0 = 70$ and $z_0 = 30$
- **Linear model is fine if x_0, y_0 and z_0 close to equilibrium**



Linear Mathematical Model of Population Growth

- **Modification of linear model**

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$$\underbrace{\begin{pmatrix} x_{t+1} - 102.78 \\ y_{t+1} - 83.33 \\ z_{t+1} - 24.86 \end{pmatrix}}_{=:\vec{v}_{t+1}} = \underbrace{\begin{pmatrix} 0.38 & -0.10 & 0.00 \\ 0.25 & 1.00 & -1.00 \\ 0.00 & 0.01 & 1.00 \end{pmatrix}}_{=:A} \cdot \underbrace{\begin{pmatrix} x_t - 102.78 \\ y_t - 83.33 \\ z_t - 24.86 \end{pmatrix}}_{=:\vec{v}_t}$$

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- **Initial conditions $x_0 = 100$, $y_0 = 70$ and $z_0 = 30 \Rightarrow \vec{v}_0 = \begin{pmatrix} 100-102.78 \\ 70-83.33 \\ 30-24.86 \end{pmatrix} = \begin{pmatrix} -2.78 \\ -13.33 \\ 5.14 \end{pmatrix}$**

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Characterization of Fixed Point

- **Matrix A**

$$A \approx \begin{pmatrix} 0.38 & -0.10 & 0.00 \\ 0.25 & 1.00 & -1.00 \\ 0.00 & 0.01 & 1.00 \end{pmatrix}$$

- **Eigenvalues $\lambda_1 \approx 0.43$, $\lambda_2 \approx 0.98 + 0.09i$ and $\lambda_3 \approx 0.98 - 0.09i$**
- **Absolute values of eigenvalues $|\lambda_1| = 0.43$ and $|\lambda_2| = |\lambda_3| \approx 0.98$**

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- **Diagonalization of matrix: $A = T \cdot D \cdot T^{-1}$**
 - D ... diagonal matrix with eigenvalues in diagonal**
 - T ... eigenvectors in columns**

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- Diagonalization of matrix: $A = T \cdot D \cdot T^{-1}$
 - $D \dots$ diagonal matrix with eigenvalues in diagonal
 - $T \dots$ eigenvectors in columns
- **All absolute values are less than 1 $\Rightarrow A^n = T \cdot D^n \cdot T^{-1} \xrightarrow{n \rightarrow \infty} T \cdot N \cdot T^{-1} = N$**
 N is null matrix

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 N is null matrix
- $\vec{v}_n \xrightarrow{n \rightarrow \infty} N \cdot \vec{v}_0 = \vec{0}$ and

$$\vec{v}_n = \begin{pmatrix} x_t - 102.78 \\ y_t - 83.33 \\ z_t - 24.86 \end{pmatrix} \xrightarrow{n \rightarrow \infty} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} x_t \\ y_t \\ z_t \end{pmatrix} \xrightarrow{n \rightarrow \infty} \begin{pmatrix} 102.78 \\ 83.33 \\ 24.86 \end{pmatrix}$$

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$$\lambda_2^n \approx 0.98^n \cdot e^{0.08in} = 0.98 \cdot [\cos(0.08n) + i \cdot \sin(0.08n)]$$

Characterization of Fixed Point

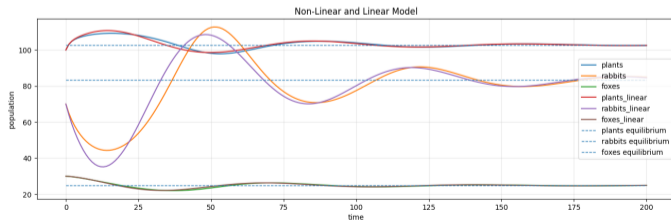
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- This cosine and sine terms explains the oscillating behaviour of solution**



Some Remarks

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We already knew at the beginning the fixed point**

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- Was all this (linearization, eigenvalues, etc.) necessary?
We already knew at the beginning the fixed point
- **Yes it is, fixed points can be**
 - **stable/attractive** (our case, all eigenvalues' absolute value < 1)
If initial condition close to equilibrium \Rightarrow solution convergence to equilibrium
 - **neutrally stable** (all eigenvalues' absolute value $= 1$)
If initial condition close to equilibrium \Rightarrow solution circles around equilibrium forever
 - **unstable/repelling** (at least one eigenvalue's absolute value > 1)
Solution diverges in most cases

Unstable Situation

- Our non-linear model again

$$x_{t+1} = 1.7x_t - 0.006x_t^2 - 0.001x_t y_t$$

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$$z_{t+1} = 0.975z_t + 0.0003y_t z_t$$

- Fixed point: $x_t \approx 102.78$, $y_t \approx 83.33$ and $z_t = 24.86$
- Initial conditions $x_0 = 100$, $y_0 = 70$ and $z_0 = 30$

Unstable Situation

- Changing the parameters a little bit

$$x_{t+1} = 1.7x_t - 0.006x_t^2 - 0.001x_t y_t$$

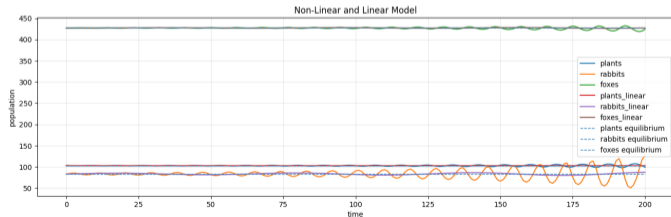
$$y_{t+1} = 0.99y_t + 0.05x_t y_t - 0.012y_t z_t$$

$$z_{t+1} = 0.975z_t + 0.0003y_t z_t$$

- New fixed point $x_t \approx 102.78$, $y_t \approx 83.33$ and $z_t \approx 427.41$
- New initial conditions $x_0 = 103$, $y_0 = 83$, $z_0 = 427$
Extremely close to fixed point

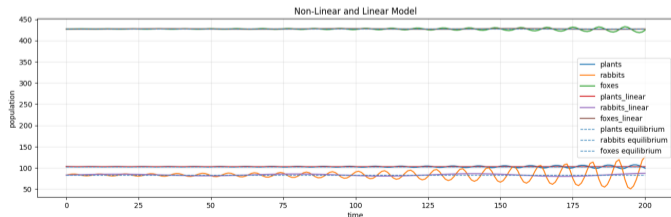
Unstable Situation

- In the plot we see the non-linear and the corresponding linear model
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Unstable Situation

- In the plot we see the non-linear and the corresponding linear model
- Both models are almost identically
- **But we see that e.g. rabbit population oscillates with growing magnitude**
- **Eigenvalues: $\lambda_1 \approx 0.035$, $\lambda_2 \approx 0.999 + 0.102i$ and $\lambda_3 \approx 0.999 - 0.102i$**
- **Absolute values of eigenvalues: $|\lambda_1| \approx 0.034$ and $|\lambda_2| = |\lambda_3| \approx 1.004 > 1$**
- **Due to $|\lambda_2| = |\lambda_3| > 1$ we get unstable situation**



Final Model without Interactions

- **Let's see what happens if model is much simpler: no interactions**
 - **Plants are not eaten by rabbits**
 - **Rabbits are not eaten by foxes**

Final Model without Interactions

- Let's see what happens if model is much simpler: no interactions
 - Plants are not eaten by rabbits
 - Rabbits are not eaten by foxes
- Our non-linear model again (interaction terms in red)

$$x_{t+1} = 1.7x_t - 0.006x_t^2 - 0.001x_t y_t$$

$$y_{t+1} = 0.99y_t + 0.003x_t y_t - 0.012y_t z_t$$

$$z_{t+1} = 0.975z_t + 0.0003y_t z_t$$

- Initial conditions $x_0 = 100$, $y_0 = 70$ and $z_0 = 30$

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- **Model without interactions**

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- Initial conditions $x_0 = 100$, $y_0 = 70$ and $z_0 = 30$ (no change)
- **New fixed point $x_t \approx 116.67$, $y_t = z_t = 0$**
- **Rabbits and foxes are dying out because $|0.99| < 1$ and $|0.975| < 1$**

Final Model without Interactions

- Due to quadratic term in

$$x_{t+1} = 1.7x_t - 0.006x_t^2$$

we get an upper bound for plant population $x_t \leq 116.67$

This is related to the famous **logistic growth**

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- In graph we see non-linear and linear model which are almost identically

